OpenDA, a generic toolbox for data assimilation in numerical modelling

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What do we mean by “data assimilation”?

Techniques and methodologies for:

- Improvement of real time forecasts
- Calibration of uncertain model parameters
- Uncertainty analysis
- Study the potential value of new observations
- Estimation of uncertain sources

“formal techniques for structured integration of data and models”
Common / “traditional” approaches

Sensitivity analysis / Model calibration:

- single parameter variation simulations → parameter optimisation
- tailored (ad-hoc / built-in) parameter optimisation routines
- generally no accounting of uncertainty
- dedicated built-in adjoint model codes; e.g. WAQAD

Model forecast improvement:

- built-in (extended) Kalman filter routines; e.g. in WAQUA (~ 1990)
- 3D-var; 4D var, dedicated for a specific model and a specific domain (mainly in atmospheric modelling)
- large investments in monitoring network to match assimilation needs

→ ad-hoc and dedicated (single purpose) developments
Example: Dutch operational storm-surge model

Steady state Kalman Filter

Kalman Gain Station Wick

Observation stations
Example: Dutch operational storm-surge model

Forecast improvement as function of forecast time

[Graphs showing forecast improvement for Hoek van Holland and Den Helder]
What is OpenDA?

- A generic toolbox for data-assimilation
  - library of data-assimilation algorithms
  - set of interfaces that define interactions between components

Why OpenDA?

- Provides an environment for development of algorithms
- Reuse of components – robustness
- Portability
- More efficient than dedicated development for each application

→ Overall cost effectiveness
OpenDA: interfacing of generic elements

need for one time definition of the interface (“wrapper”) between the process model code and OpenDA

there is full separation of process model parts and data assimilation parts
Benefits for user community and developers

- Generic applicability and flexibility
- Access to a range of available algorithms
- Access to a range of available intuitive uncertainty prescription options
- Same look and feel, independent of process model and (type of) application
- Steep learning curve
- Portability

- Efficient environment for data assimilation developers
- Easy switching between and testing of algorithms
- Re-use and therefore robustness of components
OpenDA merges the COSTA and DATools developments which started in 2002

⇒ Champion users in Deltares, VORtech, TUDelft/ EWl, plus BMT-Argoss, TNO-MEP, KNMI

Architecture is based on java – thoroughly tested

First optimisation algorithms: DUD (Ralston&Jennrich, 1978), Powell (1964), Simplex (Nelder-Mead, 1965)

First filters: EnKF, RRSQRT, ensrf, particle filters

Presently, wrappers exist for the model codes WAQUA, SWAN, Delft3D-FLOW, SOBEK-RE, FEWS, LOTOS-EUROS, CHIMERE, ...
To let a model run in an OpenDA application, the user must:

- configure the `StochModellInstance` interface:
  - Add stochastic information to parameters, computed state, and/or results
  - Get and/or Set the necessary values from and/or into the model
  - Let the model compute one or more time steps

- configure the `StochModelFactory` interface:
  - Create model instance (let the model clone itself)
Tasks of the black box wrapper

The Black Box wrapper:

- Only requires one ‘instance’ (Model Template)
  - clones the template to create instances
- Standardizes the way values are set to and retrieved from the model files
- Takes care of the stochastic aspects:
  - uncertainty specification
    - add uncertainty to parameters, computed state, and/or results
Example: OpenDA calibration of depth in DCSM

Figure 1: Dutch Continental Shelf Model: version 5 (dashed-line, grid cell ~10x10 km2, 12oW-13oE and 48oN-62o) and version 6 (grid cell ~2x2 km2, 12oW-13oE and 48oN-62oN). The right-hand side picture shows area of interest (Dutch coast) and water-level observation locations used for calibration.
Example: OpenDA calibration of depth in DCSM

\[ GoF = \frac{1}{2} \sum_{r=1}^{R_{\text{max}}} \sum_{s=1}^{S_{\text{max}}} \sum_{n=1}^{N_{\text{max}}} w_{r,s} \left( H_{r,s,n}^{\text{sim}}(t) - H_{r,s,n}^{\text{obs}}(t) \right)^2 / \left( \sigma_{H_{\text{obs}}}^2 \right) \]

above: GoF decrease with DUD iteration;  
right: Improvement of tidal results for Vlissingen
Present status

- OpenDA will be available as open source under LGPL conditions
- OpenDA association presently consists of Deltares, VORtech, TUDelft; the legal documents signed
- Presently available:
  - Windows distribution of OpenDA1.0
  - Documentation and examples
- Release date of OpenDA1.0 – Today, 11 May 2010
- Shortly (in a few weeks):
  - Linux distribution + sources of OpenDA1.0
• Release date of OpenDA1.0 – Today, 11 May 2010

• Several speakers will present further developments and examples

• Several flyers with example applications are available (in the rear of the auditorium / on website)

→ it is there for you to use, for all to share, why not give it a try?

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Comments?

Questions?